

# **TMS320C6457**

*Fixed-Point Digital Signal Processor*

**Silicon Revisions 1.0, 1.1, 1.2, 1.3, 1.4**

## **Silicon Errata**



Literature Number: SPRZ293A  
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## **TMS320C6457**

### **Fixed-Point Digital Signal Processor**

### **Silicon Revisions 1.0, 1.1, 1.2, 1.3, 1.4**

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## **Introduction**

This document describes the silicon updates to the functional specifications for the TMS320C6457 fixed point digital signal processor. See the device-specific data manual, *TMS320C6457 Fixed Point Digital Signal Processor* data manual (literature number [SPRS582](#)) for more information.



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**Note**—TMS320C6457 Silicon Revision 1.1 was a manufacturing process change. No design changes were made from revision 1.0 to revision 1.1. All advisories for C6457 silicon revision 1.0 also apply to revision 1.1.

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## **Device and Development Support Tool Nomenclature**

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all DSP devices and support tools. Each DSP commercial family member has one of three prefixes: TMX, TMP, or TMS (e.g., TMS320C6457GMH). Texas Instruments recommends one of two possible prefix designators for its support tools: TMDX and TMDS. These prefixes represent evolutionary stages of product development from engineering prototypes (TMX/TMDX) through fully qualified production devices/tools (TMS/TMDS).

Device development evolutionary flow:

- |            |  |
|------------|--|
| <b>TMX</b> | Experimental device that is not necessarily representative of the final device's electrical specifications                           |
| <b>TMP</b> | Final silicon die that conforms to the device's electrical specifications but has not completed quality and reliability verification |
| <b>TMS</b> | Fully-qualified production device  |

Support tool development evolutionary flow:

- |             |   |
|-------------|---|
| <b>TMDX</b> | Development-support product that has not yet completed Texas Instruments internal qualification testing |
| <b>TMDS</b> | Fully-qualified development-support product   |

TMX and TMP devices and TMDX development-support tools are shipped against the following disclaimer:

**Developmental product is intended for internal evaluation purposes.**

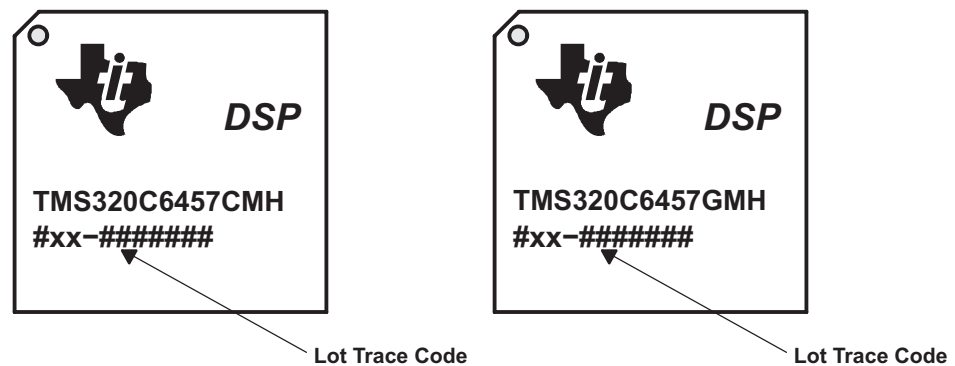
TMS devices and TMDS development-support tools have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (TMX or TMP) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

## Package Symbolization and Revision Identification

The device revision can be determined by the lot trace code marked on the top of the package. The location of the lot trace code for the CMH and GMH packages is shown in [Figure 1](#). Figure 1 also shows an example of C6457 package symbolization.

**Figure 1 Lot Trace Code Examples for TMS320C6457 (CMH and GMH Packages)**



Silicon revision correlates to the lot trace code marked on the package. This code is of the format #xx-#####. If xx is **10**, then the silicon is revision 1.0. [Table 1](#) lists the silicon revisions associated with each lot trace code for the C6457 devices.

**Table 1 Lot Trace Codes**

Lot Trace Code (xx)	Silicon Revision	Comments
14	1.4	Silicon revision 1.4
13	1.3	Silicon revision 1.3
12	1.2	Silicon revision 1.2
11	1.1	Silicon revision 1.1
10	1.0	Initial silicon revision
<b>End of Table 1</b>		

The C6457 device contains multiple read-only register fields that report revision values. The JTAG ID (JTAGID), Megamodule Revision ID (MM\_REVID) and CPU Control Status (CSR) registers allow the customer to read the current device and CPU level revision of the C6457.

The JTAG ID register (JTAGID) is a read-only register that identifies to the customer the JTAG/Device ID. The value in the VARIANT field of the JTAG ID Register changes based on the revision of the silicon being used.

The Megamodule Revision ID register (MM\_REVID) is a read-only register that identifies to the customer the revision of the C64x+ Megamodule. The value in the VERSION field of the Megamodule Revision ID Register changes based on the version of the C64x+ Megamodule implemented on the device. More details on the Megamodule Revision ID register can be found in the *TMS320C6457 Fixed Point Digital Signal Processor* data manual (literature number [SPRS582](#)).

The CPU Control Status Register (CSR) contains a read-only REVISION\_ID field that identifies to the customer the revision of the CPU being used. More information about the CPU Control Status Register can be found in the *TMS320C64x+ DSP CPU and Instruction Set Reference Guide* (literature number [SPRU732](#)).

[Table 2](#) shows the contents of the CPU Control Status Register CPU\_ID and REVISION\_ID fields, C64x+ Megamodule MM\_REVID Register REVISION field, and the JTAGID register VARIANT field for each silicon revision of the C6457 device.

**Table 2 Silicon Revision Variables**

Silicon Revision	CPU CSR Register	C64x+ Megamodule MM_REVID Register	C6457 JTAGID Register
1.4	CSR[CPU_ID] = 10h CSR[REVISION_ID] = 00h	Rev. 5.2 MM_REVID[REVISION] = 0002h	JTAGID[VARIANT] = 3h
1.3	CSR[CPU_ID] = 10h CSR[REVISION_ID] = 00h	Rev. 5.1 MM_REVID[REVISION] = 0001h	JTAGID[VARIANT] = 2h
1.2	CSR[CPU_ID] = 10h CSR[REVISION_ID] = 00h	Rev. 5.0 MM_REVID[REVISION] = 0000h	JTAGID[VARIANT] = 1h
1.1	CSR[CPU_ID] = 10h CSR[REVISION_ID] = 00h	Rev. 5.0 MM_REVID[REVISION] = 0000h	JTAGID[VARIANT] = 0h
1.0	CSR[CPU_ID] = 10h CSR[REVISION_ID] = 00h	Rev. 5.0 MM_REVID[REVISION] = 0000h	JTAGID[VARIANT] = 0h
<b>End of Table 2</b>			

More details on the JTAG ID and Megamodule Revision ID Registers can be found in the *TMS320C6457 Fixed Point DSP* data manual (literature number [SPRS582](#)).

## Silicon Updates

[Table 3](#) lists the silicon updates applicable to each silicon revision. For details on each advisory, click on the link below.

**Table 3** Silicon Revisions 1.4, 1.3, 1.2, 1.1, and 1.0 Updates

Silicon Update Advisory	See	Applies To Silicon Revision				
		1.4	1.3	1.2	1.1	1.0
EMAC Boot Issue	<a href="#">Advisory 1</a>				X	X
EDMA3CC COMPACTV Issue	<a href="#">Advisory 2</a>				X	X
SRIO Port0 Reset Issue	<a href="#">Advisory 3</a>	X	X	X	X	X
SRIO Outbound ACKID Issue	<a href="#">Advisory 4</a>	X	X	X	X	X
SRIO Bootloader Issue	<a href="#">Advisory 5</a>				X	X
DMA Access to L2 SRAM May Stall When the DMA and the CPU Command Priority is Equal	<a href="#">Advisory 6</a>	X	X	X	X	X
DMA Corruption of External Data Buffer Issue	<a href="#">Advisory 7</a>	X	X	X	X	X
DMA Corruption of L2 RAM Data Issue	<a href="#">Advisory 8</a>			X	X	X
L2 Victim Traffic Due to L2 Block Writeback During Any Pending CPU Request	<a href="#">Advisory 9</a>			X	X	X
L1P\$ Miss May Block SDMA Accesses (Asymmetric Mode Only)	<a href="#">Advisory 10</a>		X	X	X	X
Manual Cache Coherence Operation Usage Note	<a href="#">Usage Note 1</a>	X	X	X	X	X
<b>End of Table 3</b>						

## Advisory 1

## EMAC Boot Issue

**Revision(s) Affected:** 1.1, 1.0

**Details:** The EMAC ready announcement frame is not transmitted when the C6457 device is booted in master and slave modes.

When the DSP is booted in EMAC master/slave boot modes (boot modes 4, 5), the DSP transmits an Ethernet Ready Announcement (ERA) frame in the form of a BOOTP request. The BOOTP request is intended to inform the host server that the DSP is ready to receive boot packets. The ERA frame packet is described in more detail in the TI User's Guide *TMS320C645x/C647x DSP Bootloader* (literature number [SPRUEC6](#)).

Texas Instruments will fix the Ethernet Ready Announcement frame transmission in the next silicon revision for C6457 device.

**Workaround 1:** Have the host that is responsible for sending the boot packets broadcast a small boot table with the program that is shown in the example below. This will cause any C6457 device to restart the EMAC boot procedure (without configuring the MAC peripheral again) and re-transmit the ERA.

Re-send ERA packet code:

```

BOOT_REENTRY_ADDR .equ 03c000110h
BOOT_EMAC_OPT .equ 01088480Ah

    MVKL BOOT_EMAC_OPT, A1
    MVKH BOOT_EMAC_OPT, A1

    MVKL 0x00000026, A4 ;overwrite option field in EMAC bootparam
    MVKH 0x00000026, A4
    STH A4, *A1
    NOP 4

    MVKL BOOT_REENTRY_ADDR, B3
    MVKH BOOT_REENTRY_ADDR, B3
    BNOP B3, 5

```

**Workaround 2:** The host server would need to rely on prior knowledge of the DSP MAC address to transmit boot packets to the correct DSP. The DSP will be ready to receive EMAC boot packets within 2 ms following deassertion of reset.

In the scenario where the boot server reads the MAC address of the DSP from the ERA packet, the procedure would need to be changed. After some customer dependant delay where the ERA is not received, the host sends the broadcast packet with the payload described in Workaround 1.

**Advisory 2**
**EDMA3CC COMPACTV Issue**

**Revision(s) Affected:** 1.1, 1.0.

**Details:** A bug has been found inside the EDMA3 channel controller (EDMA3CC). The logic for decrementing the completion request active (COMPACTV) counter is incorrect for devices having six or more EDMA3 transfer controllers (EDMA3TCs). Therefore, the C6457 device is affected by this bug.

The COMPACTV field inside the channel controller status register (CCSTAT) indicates the count for the number of outstanding transfer requests requiring completion status that have been submitted to the transfer controllers. The channel controller increments this count every time a transfer request (TR) is submitted and is programmed to report completion (the TCINTEN or TCCHEN, or the ITCINTEN or ITCCHEN bits in OPT in the parameter entry associated with the TR are set). The counter decrements for every valid transfer completion code (TCC) received back from the transfer controllers. The bug occurs because the channel controller decrements the counter by an insufficient value when multiple responses are received concurrently from multiple (two or more) transfer controllers. Thus, the counter may gradually increase over time until it saturates at 0x3F.

If at any time the count reaches a value of 0x3F, the channel controller does not service new TRs until the count is less than 0x3F (which will happen when a transfer completion code is received from a transfer controller for an in-flight request). Once the state is reached where the counter is close to the saturation value of 0x3F, the performance of the EDMA decreases dramatically. This decreased performance happens because the channel controller will artificially limit its number of TRs in flight to the COMPACTV saturation value thereby preventing full usage of the available TCs. When the count reaches 0x3F, the TCCERR bit is set in the channel controller error register (CCERR), causing an error interrupt when enabled.

**Workaround:** The workaround is achieved by having the DSP directly program one of the transfer controllers (bypassing the channel controller) with a transfer request that requires completion. This request avoids the COMPACTV increment (because TC is programmed directly) and forces a COMPACTV decrement when the TC responds to the CC with the completion signaling.

**A specific transfer controller and a specific TCC value should be dedicated in the system for this workaround.** TC4 or TC5 is suggested because their connectivity is identical. However, the specific TC should be selected based on the end-system usage.

The DSP should poll the COMPACTV field often enough such that the counter is not allowed to exceed 0x30. The actual COMPACTV polling interval may need to be set through experimentation on the specific end system, because the rate of increment of the counter is system- and load-specific.

Upon polling, if the value of the COMPACTV field is greater than a certain threshold (0x20 is suggested), then the DSP should program the TC with a COMPACTV decrement transfer. Upon completion of that transfer (as signaled in the CC IPR register) the COMPACTV field should be re-checked, and another COMPACTV decrement transfer submitted until the value of the counter is less than the threshold.



**Note**—Care must be taken such that the software does not over-decrement the counter because at the time of polling, multiple requests may be in flight in the system and may result in additional decrements compared to the current observed value. If too many decrements occur, the counter may roll under from 0x0 to 0x3F and accidentally result in saturation of the counter. This is why a value of 0x20 is suggested as the threshold value (sufficiently large with respect to the number of actual requests that may be outstanding).

This workaround requires that a specific TC instance is dedicated to the COMPACTV decrement transfer. The reason is that, depending on the nature of the traffic on a given queue/TC, it may be difficult to control the timing of the normal CC TR submission to that TC versus the DSP programming of that TC. There is no hardware protection to prevent corruption of the TC registers in the case that both CC and DSP software attempt to program the TC simultaneously.

For the base addresses of the TCs, see the *TMS320C6457 Fixed Point Digital Signal Processor* data manual (literature number [SPRS582](#)). A brief summary of the TC registers to be configured is provided in [Table 4](#).

**Table 4 TC Registers Summary**<sup>1</sup>

Address	Register Description	Suggested Value
TCx Base + 0x0200	Prog Set Options	See the Prog Set Options Register description below
TCx Base + 0x0204	Prog Set Src Address	See Prog Set Src/Dst Address Register description below
TCx Base + 0x0208	Prog Set Count	0x00010004 (ACNT = 4 and BCNT = 1)
TCx Base + 0x020C	Prog Set Dst Address	See Prog Set Src/Dst Address Register description below
TCx Base + 0x0210	Prog Set B-Dim Idx	0x0 (don't care because BCNT = 1). Writing to the PBIDX register triggers the transfer. Thus, this register should be written.
<b>End of Table 4</b>		

1. The five registers listed in [Table 4](#) should be written in the sequence shown (i.e., top to bottom). The last write, to the Prog Set B-Dim Idx register, triggers the transfer.

### Prog Set Options Register

The Prog Set Option register is shown in [Table 4](#). The TCINTEN bit should be set to 0x1. The TCC code should be set to some known value that is not used by other requests in the system. The other fields should be set to 0x0. Upon completion of the transfer, the TCC value will be set in the corresponding bit in the IPR/IPRH registers. The software should poll for this bit in the IPR/IPRH registers and then clear it with the ICR/ICRH registers before programming the next COMPACTV decrement transfer.

**Advisory 3*****SRIO Port0 Reset Issue***

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**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** The SERDES macro for SRIO should allow reset of individual 1× ports without affecting the state of the other operational ports. There are dedicated MMR bits to reset 1× ports, which are the BLK<sub>n</sub>\_EN (n=5..8) at offsets 0x60, 0x68, 0x70 and 0x78 for C6457. However, the BLK5\_EN, which controls reset for port0, also resets all other ports. Therefore, it is impossible to reset port0 without affecting all other ports.

**Workaround 1:** There is no workaround for this advisory.

**Advisory 4*****SRIO Outbound ACKID Issue***

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**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** The OUTBOUND\_ACKID field of the RIO\_SP(n)\_ACKID\_STAT register should be updated by hardware each time a packet is sent out. The value should reflect the ACKID value to be used on the next transmit packet. This field is being updated by hardware as expected. The field can be also written by software and these writes also succeed. However, a hardware error prevents this field from being read. The OUTBOUND\_ACKID will always read as 0. This problem does not impact link operation.

**Workaround 1:** There is no workaround for this advisory.

**Advisory 5*****SRIO Bootloader Issue***

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**Revision(s) Affected:** 1.1, 1.0

**Details:** Silicon revisions 1.0 and 1.1 of the C6457 device use the v1.5 bootloader. In SRIO boot mode, when 4× mode falls back to 1× mode in certain hardware configurations, the boot does not operate correctly. The boot ROM code erroneously expects the port to initialize (Port\_ok = 1) before the SRIO discovery timer (length of time it tries to establish a 4× connection before falling back to 1×) has a chance to expire. When this situation occurs, the DSP goes to the exception handler and waits until the program counter is written with something other than 0. So, even though the program load and Doorbell interrupt through SRIO were successful, the DSP will just sit there and not jump to the application image entry point.

**Workaround 1:** After the RapidIO system host sends the application image, the host needs to write an application entry point to address 0x009FFFFC and then send the doorbell interrupt.

## Advisory 6

### **DMA Access to L2 SRAM May Stall When the DMA and the CPU Command Priority is Equal**

**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** The L2 memory controller in the C64x+ Megamodule has programmable bandwidth management features that are used to control bandwidth allocation for all requestors. There are two parameters to control this feature: command priority and arbitration counter MAXWAIT values.

Each requestor has a command priority and the requestor with the higher priority wins. However, there are also counters associated with each requestor that track the number of cycles each requestor loses arbitration. When this counter reaches a threshold (MAXWAIT), which is programmed by the user (or default value), the losing requestor gets an arbitration slot and wins for that cycle.

There are four such requestors: CPU, DMA (SDMA and IDMA), user cache coherency operation, and global cache coherence. Global-coherence operations are highest priority, while user-coherence operations are lowest priority. However, there is active arbitration done for the CPU and the DMA (SDMA/IDMA) commands. The priority for DMA commands comes from an external master as part of the SDMA command or a programmable register, IDMA1\_COUNT, in the C64x+ Megamodule for IDMA commands. The priority for CPU accesses to L2 is in a programmable register, CPUARBU, in the C64x+ Megamodule. For the default priority values, see [Table 5](#).

**Table 5 C6457 Default Master Priorities**

<b>Master</b>	<b>Default Master Priorities 0 = Highest Priority 7 = Lowest Priority</b>	<b>Priority Control</b>
EDMA3TCx	0	QUEPRI.PRIQx <sup>1</sup> (EDMA3 Register)
SRIO (Data Access)	0	PER_SET_CNTL.CBA_TRANS_PRI <sup>2</sup>
SRIO (Descriptor Access)	1	PRI_ALLOC.SRIO_CPPI
EMAC	1	PRI_ALLOC.EMAC
HPI	2	PRI_ALLOC.HOST
<b>End of Table 5</b>		

1. EDMA3 Register

2. SRIO Register

The L2 memory controller is supposed to give equal bandwidth to the DMA and the CPU, by alternating between the two for arbitration. Instead, the L2 memory controller gives larger bandwidth allocation to the CPU accesses when the DMA and the CPU priorities are the same. The CPU commands keep winning arbitration over the DMA as long as there are no other internal conditions (stalls, etc.) that force the DMA to win arbitration. This typically happens when CPU accesses keep the L2 memory controller

busy every cycle. Hence, the DMAs stall until the stream of CPU accesses completes. For example, if a continuous stream of L1D write misses to L2 keep the L2 memory controller busy every cycle, the DMAs stall for the entire duration of the write miss stream.




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**Note**—When the SDMA has finished sending all of its commands to the L2 controller the C64x+ Megamodule drops the effective transfer priority down to 7 if no further commands are in the pipeline. This condition happens when there is a single word access, a burst of less than 32B with no other SDMA commands pending, or for only the last 64B of a burst that is greater than 64B with no other SDMA commands pending. This effective priority level is what the L2 controller uses to arbitrate these SDMA commands with the CPU, irrespective of what the actual programmed priority value is of the master peripheral. This means that if the CPU is programmed to priority 7, via the CPUARB register, this issue will be triggered. Therefore, priority 7 is not a valid priority level for CPU. If for any reason this *demoted* transfer is still pending upon initiation of another transfer, it will automatically inherit the priority of that new transfer and be pushed through such that it does not stall the new transfer.

---

**Workaround 1:** Set the CPU and the DMA commands to L2 on different priorities. As noted above, Priority 7 is not a valid priority for the CPU.

## Advisory 7

## DMA Corruption of External Data Buffer Issue

**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** Under a specific set of circumstances, an L1D snoop-write will update an unintended L1D cache line. This leads to a corrupted line in L1D, and can lead directly to program misbehavior. If the corrupted line is then modified by a CPU write accesses, a subsequent victim writeback from L1D could commit the corrupted line to lower levels of memory. Two key requirements for this bug are:

- DMA writes to buffers in UMAP1 only
  - This must be cached and unmodified in L1D (read by CPU but not yet written to)
  - The L2 memory is typically shared across the two unified memory access ports, UMAP0 and UMAP1. This bug occurs only if the buffer is located in UMAP1. For the UMAP1 allocation on the C6457 device, see [Table 6](#).
- CPU reads from external, cacheable address
  - UMAP0 and UMAP1 are the two ports on the C64x+ Megamodule used to connect the L2 Memory controller and the physical RAMs. For the UMAP1 allocation on the C6457 device, see “[Appendix C—UMAP0 and UMAP1 Addresses Ranges](#)”.
  - For information on L1D cache coherence protocol, see section 3.3.6, Cache Coherence Protocol, in the *C64x+ DSP Megamodule Reference Guide* (literature number [SPRU871](#)).
  - DMA in the following description refers to all non-CPU requestors. This includes IDMA, EDMA, and any other master in the system.

Under the specific set of circumstances listed below, a snoop-write updates an L1D cache line other than the one intended. This leads to a corrupted line in L1D. Corruption happens only when the buffer in UMAP1 is cached in L1D while the CPU is consuming external, cacheable data. The prerequisite before the window where the bug occurs is:

- The CPU reads an L2 location in UMAP1 and has not modified (written) to the same location before the window where the bug occurs.
  - Because of this, a 64B cache line is allocated clean in L1D (referred to here as Cache Line A).

The following steps must all occur concurrently to see the issue (note that the concurrency is within the cache subsystem, so events visible at the CPU or the DMA are not occurring during the same exact cycle):

1. The L1D is currently processing a snoop request or some other request that prevents it from accepting new snoops. This could have been caused by any of the following that is still being processed from previous actions:
  - DMA read/write
  - L1D read/invalidate
  - L1D read + victim
2. The DMA writes to Cache Line A, mentioned in the prerequisite above. This means that it is not necessarily the same exact address, but must be within the same 64B cache line.
  - As a result, a snoop-write request is generated but it is blocked because the L1D is still busy with Step 1.

3. The CPU reads from a cacheable, external memory (e.g., DDR) that is a set match to Cache Line A (referred to here as Cache Line B). Determining if two addresses are a set match can be done by comparing certain bits of two addresses. The mapping of an address to a location in L1D cache is shown in [Figure 7](#).
  - Please see [Appendix B—Determining If Two Addresses are a Set Match](#) for instructions on how to determine if two addresses are a set-match.

This results in a cache miss from the CPU for an external address and sends a read request to L2 cache for the line (and possibly to the external source on an L2 cache miss or if no L2 cache is present).

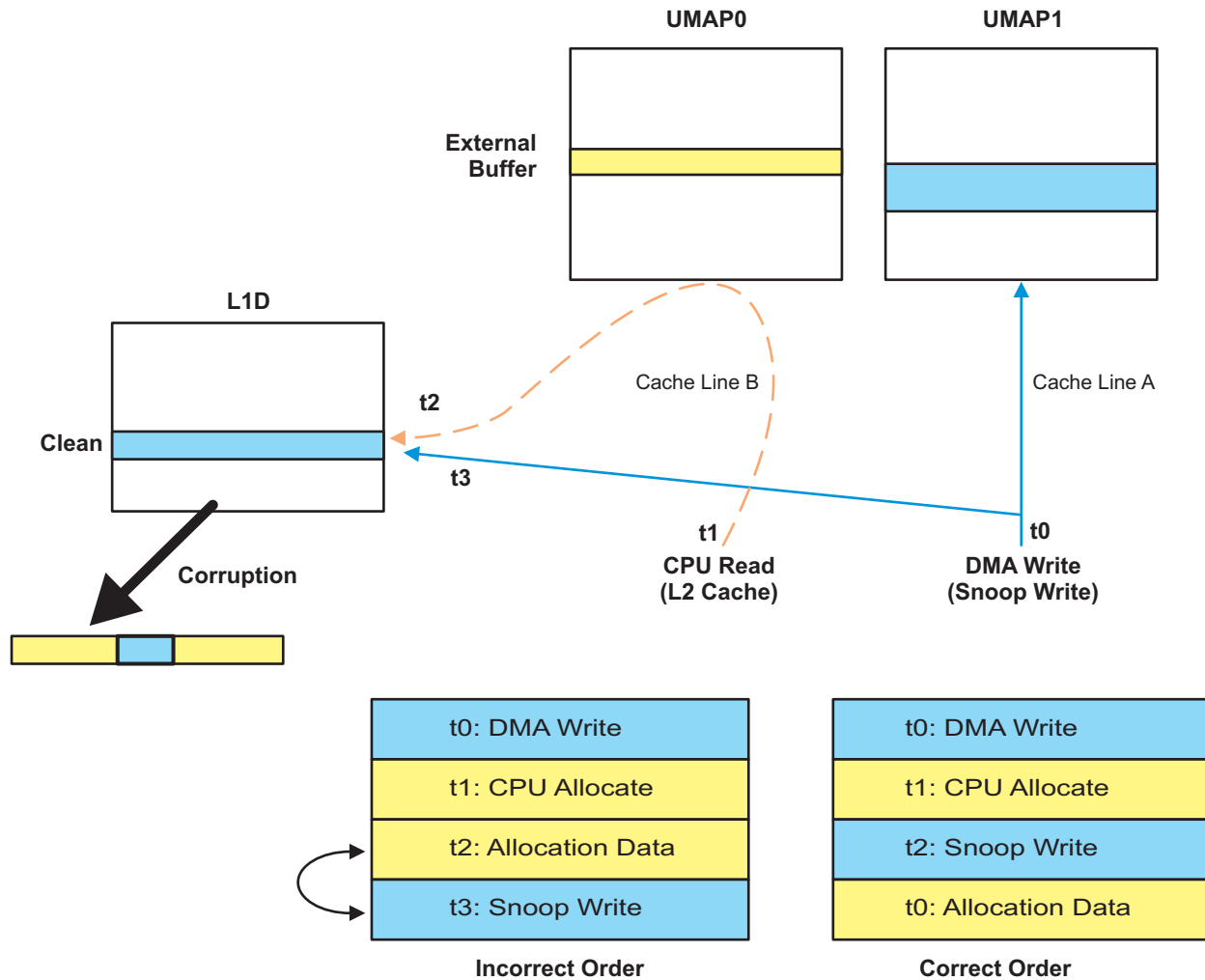
The results of the above cause the following to occur:

- L2 sends both the return data for the L1D read miss request (response of Step 3 above) and the data for the snoop-write (response of Step 2 above). The L1D commits the snoop-write data after the L2 return data.
- As a result, L1D now holds the wrong data for the external address (Cache Line B) and commits the data to cache. Cache Line B remains marked *clean*. If the program does not write to the uncorrupted portion of the line and does not read the corrupted portion of the line, the corruption goes unnoticed. If the program writes to the uncorrupted portion of the line, the corrupted data gets written back to L2 cache and/or external memory. Otherwise, the corruption disappears when L1D discards the line.
- Cache lines holding external addresses are the only cache lines that exhibit corruption. Corruption happens only when DMA buffers in UMAP1 get cached in L1D. In addition, corruption happens only when the DMA buffer is clean, meaning that it gets discarded without generating a victim. Thus, this affects buffers where the DMA writes and the CPU reads. It does not affect buffers that the CPU only writes and/or DMA only reads.

One can identify this bug unambiguously by examining the corrupted memory range in CCStudio using the cache tag viewer. The corrupted data shows up in the include L1D view in a memory window, but not in the exclude L1D view. The cache tag viewer should indicate that the line is also *clean* and the corrupt data should also be visible in its intended destination, which must be in UMAP1 and map to the same L1D set as the corrupted line.

Figure 2 shows the flow of these operations, the incorrect order that causes the issue, and the correct order to avoid the issue. The solid line is Cache Line A and the dashed line is Cache Line B.

Figure 2 Cache Line Operations Flow



All of the conditions described above must be true to see the issue. The workarounds focus on picking one of the conditions and removing it so that the user does not need to worry about the other condition.

TI proposes starting with workaround 1 as an immediate fix. The other workarounds that follow may provide a solution with reduced overhead and/or simplified implementation depending on the system scenario.

**Workaround 1:** Write Back and Invalidate DMA Buffers

L1D corruption occurs when DMA writes to a buffer in UMAP1 that is also cached in L1D, at the same time the L1D is discarding the buffer. Thus, this affects buffers where the DMA writes, and the CPU reads. It does NOT affect buffers that the CPU only writes and/or the DMA only reads.

To prevent this sort of race condition, programs should discard in-bound DMA buffers in UMAP1 immediately after use, and keep a strict policy of *buffer ownership*, such that a given buffer is owned only by the CPU or the DMA at any given time.

This model assumes the following steps:

1. DMA fills the buffer during a period when the CPU does not access it
2. DMA engine or other mechanism signals to the CPU that it has finished filling the buffer.
3. CPU operates on the buffer, reading and writing to it as necessary. The DMA does not access the buffer at this time.
4. CPU relinquishes control of the buffer, so that DMA may refill it
  - This last step may be an implicit step in many implementations if the period between refills is much longer than the time it takes the CPU to process the refilled buffer.

To implement this workaround, programmers must write back and invalidate the buffer from L1D cache after step 3 and before step 4. This simply eliminates the prerequisite for the bug to occur should another DMA in the future be a set match to the reads that the CPU just performed.

There are multiple mechanisms for doing this, but the most straightforward is to use the L1D block cache writeback-invalidate mechanism via L1DWIBAR / L1DWIWC.

Provided with this document is the recommended implementation (see the code listing for `lld_block_wbinv.asm` in section of [Appendix A—Code Examples](#)). It can be invoked as follows:

```
void lld_block_wbinv(void *base, size_t byte_count);
```

To writeback-invalidate a C array, one could then do:

```
char array[SIZE];

/* ... */

lld_block_wbinv(&array[0], sizeof(array));
```

Programmers should insert such a call whenever the code is done with a particular DMA buffer in UMAP1, before the DMA controller can refill it. The `lld_block_wbinv()` function is non-interruptible. Its overhead is proportional to the size of the buffer.

**Workaround 2:** Make DMA Buffers Dirty After Use

The errant snoop-write occurs only when the DMA buffer in L1D has not been modified. This is due to the additional snoop checking mechanisms associated with tracking victims as they leave L1D.

Therefore, another workaround is to mark DMA buffers as *dirty* before releasing them. This will generate additional victims whenever the buffer gets pushed out of L1D. It will also block the errant snoop-write.

This workaround assumes a similar model to workaround #1. In place of `l1d_block_wbinv()`, call the function `make_dirty()` provided in section of [Appendix A—Code Examples](#). The `make_dirty()` function reads one byte from each cache line of the buffer and writes the same value back to it immediately.

The function is called as follows:

```
void make_dirty(void *base, size_t byte_count);
```



**Note**—This workaround is *not* acceptable if the DMA could be writing to the buffer at the same time `make_dirty()` gets called. The process of making the cache line dirty requires reading and writing within the buffer and so the CPU writes could overwrite the inbound data from the DMA.



**Note**—Please see [Advisory 8](#). “DMA Corruption of L2 Ram Data” for more information. This workaround may cause the application to be affected by that issue.

**Workaround 3:** Do Not Cache Data from External Memory in L1D

If the user’s program only makes a small number of data accesses to external memory, consider marking the data portions of external memory as *non-cacheable*. This prevents caching copies of external memory in L1D cache.

Alternately, freeze the L1D cache around each access to an external address, to prevent the line from allocating in L1D. The `long_dist_load_word` function (please see the code listing for `ldld.asm` provided in section of [Appendix A—Code Examples](#)) is suitable for isolated accesses. For larger accesses, such as reading a block, other techniques may be more appropriate.

The incorrect snoop-write only occurs when the L1D read miss involved is to an external address. The snoop-write corrupts the newly cached copy in L1D. If all accesses to external data memory are non-cacheable or occur while L1D is frozen, this prevents copies from being stored in L1D.

**Workaround 4:** Allocate DMA Buffers in L1D RAM or UMAP0

If possible, move DMA buffers that the CPU reads directly out of UMAP1 to either UMAP0 or L1D RAM. A table showing UMAP0 addresses of the C6457 can be found in [Table 6](#). DMA buffers that the CPU does not access directly can remain in UMAP1 safely, as these will not generate snoops.

**Table 6 UMAP0 Address Range for C6457**

UMAP0	Address Range <sup>1</sup>
RAM	0x00900000 - 0x009FFFFFF
<b>End of Table 6</b>	

1. Please note that L2 cache, if used, is a portion of the address range.

If the user's set of in-bound DMA buffers does not fit in L1D RAM and UMAP0 statically, consider paging buffers from UMAP1 to either UMAP0 or L1D RAM. That is, allow DMA to write to buffers in UMAP1 freely, but never read them directly from the CPU. Instead, use IDMA to copy a buffer from UMAP 1 to either UMAP0 or L1D RAM before using it.

The IDMA1 utility functions (please see the code listing for `idma1_util.asm` provided in the section of [Appendix A—Code Examples](#)) can be used for copying data with the IDMA controller.

## Advisory 8

## DMA Corruption of L2 Ram Data

**Revision(s) Affected:** 1.2, 1.1, 1.0

**Details:** Under a specific set of circumstances, a snoop-write updates an unintended L2 RAM location. This is a result of a corrupted L1D cache writeback, and can lead directly to program misbehavior. If that line is then modified by CPU accesses, a subsequent victim writeback from L1D could commit this corrupted line to lower levels of memory. Three key requirements for this bug are:

- The DMA reads or writes to buffers in L2 SRAM.
  - This must be cached and modified in L1D (read and written by the CPU).
- The CPU reads from any L2 or external, cacheable address.
- A second DMA write to the same cache line address (within 64B) in L2 RAM that the CPU is reading from.



**Note**—For Information on L1D cache coherence protocol, see section 3.3.6, Cache Coherence Protocol, in the C64x+ DSP Megamodule Reference Guide (SPRU871).



**Note**—The DMA in the following description refers to all non-CPU requestors. This includes IDMA, EDMA, and any other master in the system.

Under the specific set of circumstances listed below, a snoop-write results in a data corruption in L2 RAM. This bug exists only when L1D evicts a dirty line from its cache while allocating a new line to the same set/way. Both lines must be from L2 SRAM in either UMAP0 or UMAP1 (For the UMAP0 and UMAP1 allocation on the C6457 device, see “[Appendix C—UMAP0 and UMAP1 Addresses Ranges](#)”). The bug occurs when there is a DMA to L2 for the allocated (clean) line and a DMA to or from the victim (dirty) line. The L2 sends the DMA request as a snoop-read or -write to the L1D cache after it allocates the new line. When the bug occurs, the snoop-write to the allocated line corrupts the line being evicted instead. The L2 writes this corrupted victim back to L2 SRAM.

The prerequisite before the window where the bug occurs is:

- The CPU reads an L2 location and has modified (written to) the same cache line location before the window where the bug occurs. That means that it is not necessarily the same exact address that is written to, but within the same 64B cache line.
  - Because of this, a 64B cache line is allocated and dirty in L1D (referred to here as Cache Line A).

The following steps must all occur concurrently to see the issue:

1. The CPU reads from any address in L2 SRAM that is a set match to Cache Line A (to determine if a set match condition exists, see [Appendix B—Determining If Two Addresses are a Set Match](#))
  - The set match to Cache Line A is referred to here as Cache Line B.
  - This results in a cache miss from the CPU and sends a read request to L2 cache for the line (and possibly an external source if it was through L2 cache or if no L2 cache is present).
  - Because Cache Line A is dirty, a victim is prepared to be sent after Cache Line B is allocated and is held in a temporary victim data buffer
    - › Please see [Appendix B—Determining If Two Addresses are a Set Match](#) for instructions on how to determine if two addresses are a set match.
2. The DMA read or writes from/to Cache Line A, mentioned in the prerequisite above. This means that it is not necessarily the same exact address, but within the same 64B cache line.
  - As a result, a snoop-read/-write request is generated.
3. The DMA writes to Cache Line B, mentioned in Step 1. This means that it is not necessarily the same exact address, but within the same 64B cache line as Step 1.
  - As a result, a snoop-write request is generated but not immediately issued, as it is blocked by the snoop-read/-write issued in Step 2.

The results of the above cause the following to occur:

- The L1D controller receives the new line (B) back from the L2 Controller.
- If Step 2 above was a write, the snoop-write to Cache Line A updates the victim buffer correctly. If it was a read, the snoop-read returned the correct data to the DMA.
- The snoop-write to Cache Line B (Step 3 above) incorrectly updates the victim buffer instead of the newly allocated line that was returned in Step A.

As a result, the following is true:

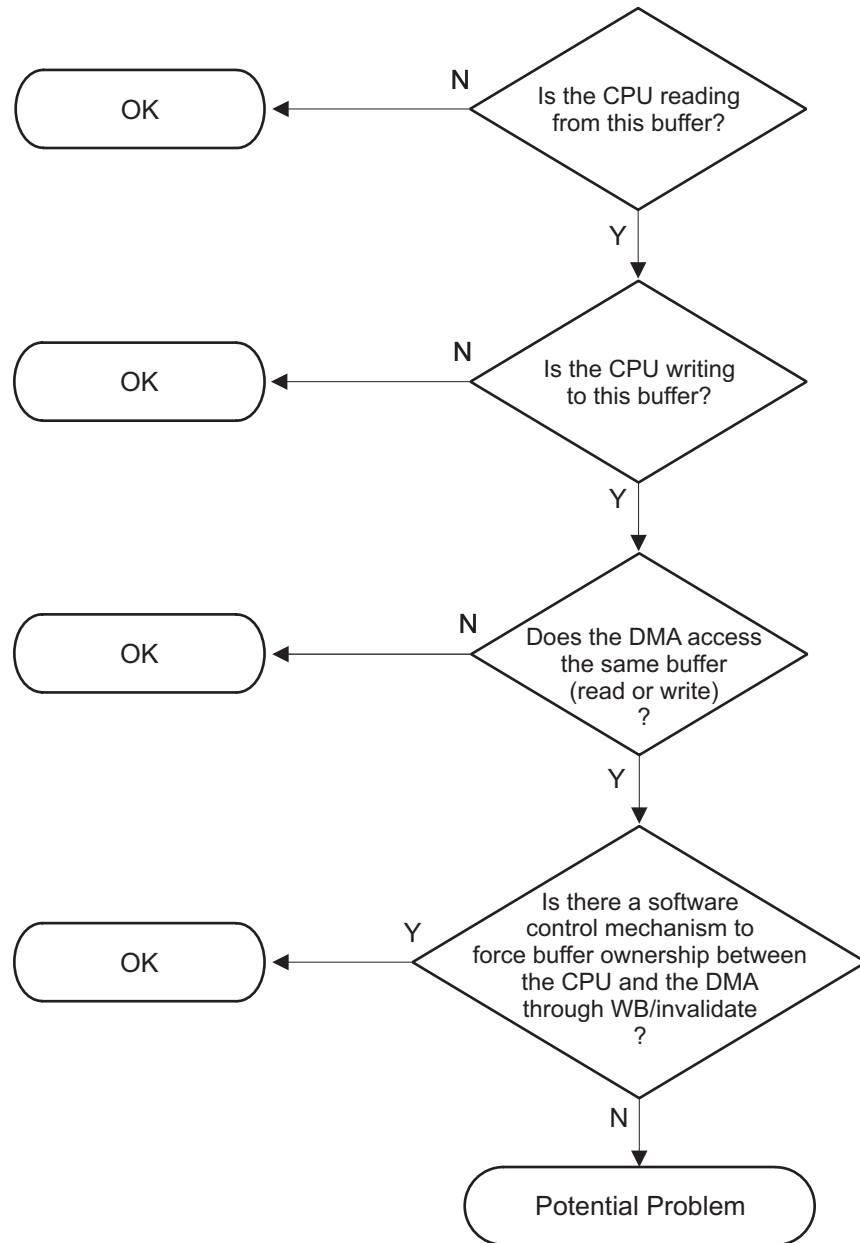
1. Cache Line A now holds data that was corrupted by Steps 3 and C above.
  - subsequent read of this data returns a corrupted value.
2. Cache Line B now holds stale data, as it was never updated with the data it was supposed to get from Steps 3 and C.
  - The CPU gets stale data (not updated).

Corruption happens only when the DMA accesses an L1D cache line that the CPU also writes to. This results in DMAs that may match victim lines leaving L1D. Thus, it can affect buffers that the CPU fills with writes and the DMA reads, as well as buffers where both the DMA and CPU write. It does not affect DMA buffers that the CPU only reads.



With all the steps above, it is fairly painful to determine if a particular buffer has the potential to see this issue. [Figure 4](#) is a simple decision tree to help make a determination for a particular buffer.

**Figure 4** Decision Tree



When using the above flowchart, if one of the *OK* fields is reached, then the buffer should not have a potential of being affected. When using the above flowchart, if one of the *Potential Problem* fields is reached, see the workarounds below.



**Note**—Figure 4 assumes that each buffer is aligned to a 64B-boundary and spans a multiple of 64B. This is because the cache line size of the L1D is 64B. If that is not the case, there is a chance that the user might still see this issue even if an *OK* state in the diagram was reached (see the Workaround for False-sharing section below).

The bug occurs when the CPU writes within the same L1D cache line that the DMA reads or writes. This can happen for multiple reasons. The following sections detail workarounds for three scenarios:

1. The CPU writes to a buffer that the DMA then reads. This could either be due to an *in-place* algorithm that operates on data brought to it by DMA or an *out-of-place* algorithm in which the CPU fills a buffer that the DMA then reads. In either case, the CPU and DMA explicitly synchronize.
2. The CPU and DMA are updating distinct or unrelated objects that happen to share a cache line. (This is sometimes called *false sharing*.) Because the objects are unrelated, the DMA and CPU are not synchronized.
3. The CPU and DMA are both writing to the same structure without external synchronization. This pattern often underlies software synchronization implementations and lockless multiprocessing algorithms.

**Workaround 1:** Workaround for Synchronizing DMA and CPU Access to Buffers

The CPU potentially triggers this bug when it reads and later writes to a buffer that the DMA also accesses (read or write). The bug can happen when the DMA accesses the affected line when the L1D cache writes it back to L2. To avoid this bug, programmers can explicitly manage coherence on the buffer so that the buffer is not present and dirty in L1D when the DMA accesses it.

To explicitly manage coherence on the buffer, programmers should adhere to the programming model described earlier: Programs should write back or discard in-bound DMA buffers immediately after use and keep a strict policy of buffer ownership such that a given buffer is owned only by the CPU or the DMA at any given time.

This model assumes the following:

1. The DMA fills the buffer during a period when the CPU does not access it.
2. The DMA engine or other mechanism signals to the CPU that it has finished filling the buffer.
3. The CPU operates on the buffer, reading and writing to it, as necessary. The DMA does not access the buffer at this time.
4. The CPU relinquishes control of the buffer so that DMA may refill it. (This may be an implicit step in many implementations if the period between refills is much longer than the time it takes the CPU to process the refilled buffer.)

To implement this workaround, programmers must write back (and optionally invalidate) the buffer from L1D cache after Step 3 and before Step 4. There are multiple mechanisms for doing this, but the most straightforward is to use the L1D block cache writeback mechanism via L1DWBAR/L1DWWC or the L1D block cache writeback-invalidate mechanism via L1DWIBAR/L1DWIWC.

The recommended implementation of this workaround requires calling the `l1d_block_wb.asm` and `l1d_block_wbinv.asm` functions (see the L1D Block Writeback and L1D Writeback-Invalidate Routines in Sections and of [Appendix A—Code Examples](#)). The functions can be invoked as follows:

```
void l1d_block_wb(void *base, size_t byte_count);
```

or

```
void l1d_block_wbinv(void *base, size_t byte_count);
```

To writeback a C array, one could then do:

```
char array[SIZE];
/* ... */
l1d_block_wb(&array[0], sizeof(array));
```

The above example could be used to writeback-invalidate as well by calling the other function. Programmers should insert such a call whenever the CPU code is done with a particular DMA buffer, before the DMA controller can refill it. The `l1d_block_wb()` and `l1d_block_wbinv()` functions are non-interruptible. The overhead is proportional to the size of the buffer.



**Note**—To ensure complete effectiveness, ensure that the DMA buffers always start on an L1D cache-line boundary (64-byte boundary) and occupy a multiple of 64 bytes. This may require increasing the size of some DMA buffers slightly. This is necessary to prevent accesses to an unrelated buffer or variable from bringing a portion of the DMA buffer back into the L1D cache.

**Workaround 2:** Workaround for *False Sharing*

This bug can occur when the CPU and the DMA both access distinct objects that share a single L1D cache line. This is often referred to as false sharing. To avoid false sharing, ensure that the DMA buffers begin on 64-byte boundaries and occupy a multiple of 64 bytes. This may require increasing the size of some DMA buffers. If an application has many small DMA buffers, consider packing these together to limit the overall growth in DMA buffer space implied by this workaround.

---

**Workaround 3:** Workaround for Buffers that the CPU and DMA Access Asynchronously

While this situation is rare in most programs, there are some cases where both the CPU and the DMA access the same structure without explicit synchronization. In some cases, this is due to the fact that said accesses are part of an algorithm that implements a synchronization primitive. Regardless of the purpose, these accesses potentially trigger this bug.

The easiest way to avoid the bug with this case is to freeze the L1D whenever the CPU reads this buffer. This prevents the buffer from allocating in the L1D cache so that the DMA never sends a snoop (read or write) to the DMC on behalf of this buffer.

Alternately, programs can always invalidate the line in L1D after reading it so that all writes to the line miss L1D and the line is never present and dirty in L1D cache. Programs can use the L1D block invalidate (L1DIBAR/L1DIWC) or L1D block writeback-invalidate (L1DWIBAR/L1DWIWC) to perform these explicit coherence operations.

**Advisory 9**
**L2 Victim Traffic Due To L2 Block Writeback During Any Pending CPU Request**

**Revision(s) Affected:** 1.2, 1.1, 1.0

**Background:** The C64x+ megamodule has a Master Direct Memory Access (MDMA) bus interface and a Slave Direct Memory Access (SDMA) bus interface. The MDMA interface provides DSP access to resources outside the C64x+ megamodule (i.e., DDR2 memory). The MDMA interface is used for CPU/cache accesses to memory beyond the level 2 (L2) memory level. These accesses include cache line allocates, write-backs, and non-cacheable loads and stores to/from system memories. The SDMA interface allows other master peripherals in the system to access level 1 data (L1D), level 1 program (L1P), and L2 RAM DSP memories. The masters allowed accesses to these memories are DMA controllers, EMAC, and SRIO. The DSP Internal Direct Memory Access (IDMA) is a C64x+ megamodule DMA engine used to move data between internal DSP memories (L1, L2) and/or the DSP peripheral configuration bus. The IDMA engine shares resources with the SDMA interface.

The C64x+ megamodule has an L1D cache and an L2 cache, both of which implement write-back data caches. The C64x+ megamodule holds updated values for external memory as long as possible. It writes these updated values, called victims, to external memory when it needs to make room for new data, when requested to do so by the application, or when a load is performed from a non-cacheable memory for which there is a set match in the cache (i.e., the non-cacheable line would replace a dirty line if cached). The L1D sends its victims to L2. The caching architecture has pipelining, meaning multiple requests could be pending between L1, L2, and MDMA. For more details on the C64x+ megamodule and its MDMA and SDMA ports, see the *TMS320C64x+ Megamodule Reference Guide* (literature number [SPRU871](#)).

[Figure 5](#) shows IDMA, SDMA, and MDMA paths. Ideally, the MDMA (the blue lines) and SDMA/IDMA paths (the orange lines) operate independently with minimal interference. Normally, MDMA accesses may stall for extended periods of time (clock cycles) due to expected system level delays (e.g., bandwidth limitations, DDR2 memory refreshes).

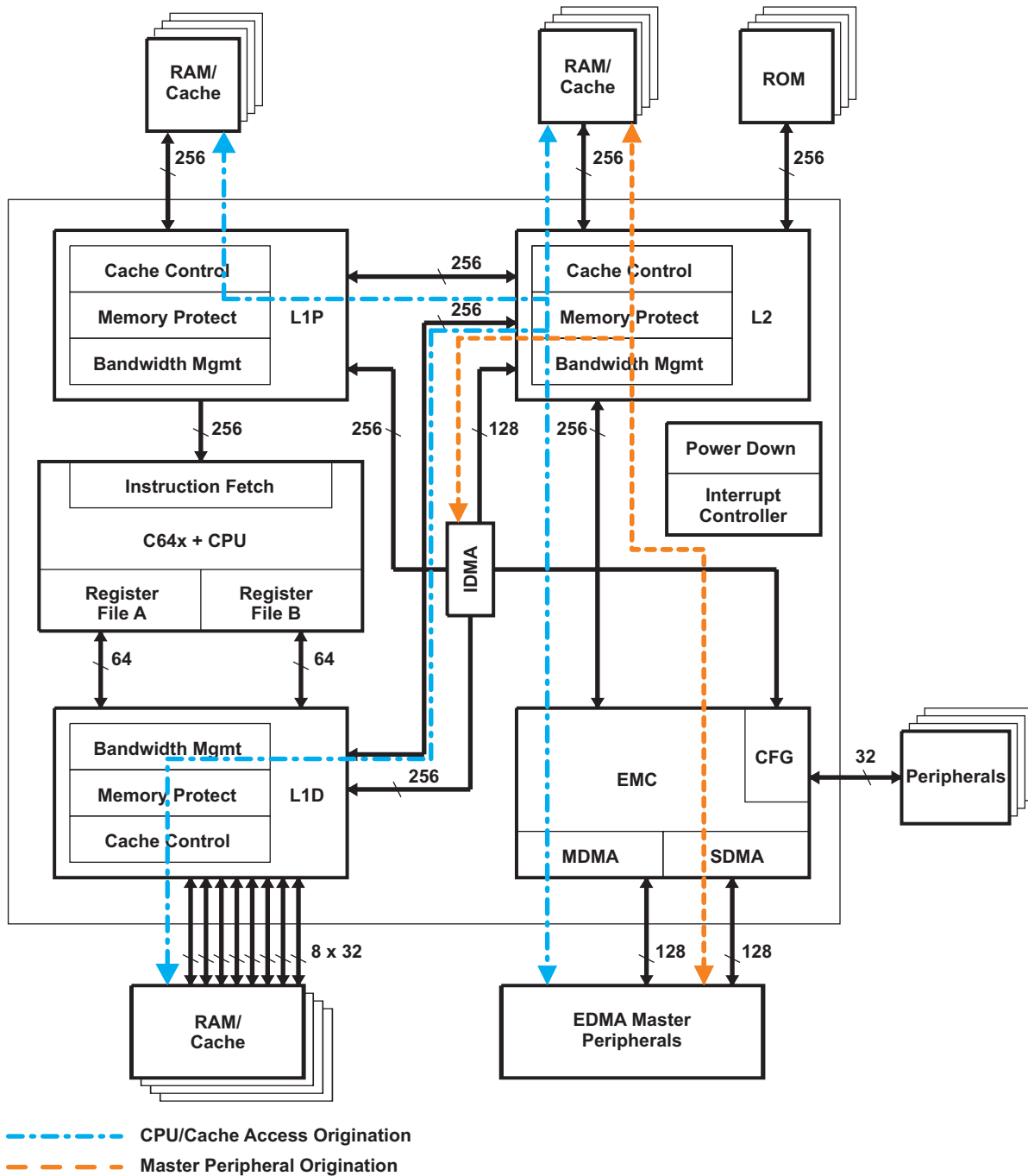
However, when using L2 as RAM, SDMA, and/or IDMA accesses to L2/L1 **may experience unexpected stalling** in addition to the normal stalls seen by the MDMA interface. For latency-sensitive traffic, the SDMA stall can result in missing real-time deadlines.



**Note**—SDMA/IDMA accesses to L1P/D will not experience an unexpected stall if there are no SDMA/IDMA accesses to L2. Unexpected SDMA/IDMA stalls to L1 happen only when they are pipelined behind L2 accesses.

Figure 5 is a simplified view for illustrative purposes only. The IDMA/SDMA path (orange lines) can also go to L1D/L1P memories and IDMA can go to the DSP CFG peripherals. MDMA transactions (blue lines) can also originate from L1P or L1D through the L2 controller or directly from the DSP.

Figure 5 IDMA, SDMA, and MDMA Paths



The duration of the SDMA/IDMA stalls depend on the quantity/characteristics of the L1/L2 cache and the MDMA traffic in the system. Therefore, it is difficult to predict if stalling will occur and for how long.

SDMA/IDMA stalling and any system impact is most likely in systems with excessive context switching, L1/L2 cache miss/victim traffic, and heavily loaded EMIF.

Use the following steps to determine if SDMA/IDMA stalling is the cause of real-time deadline misses for existing applications. Situations where real-time deadlines may be missed include loss of McBSP samples and low peripheral throughput.

1. Determine if the transfer missing the real-time deadline is accessing L2 or L1D memory. If not, then SDMA/IDMA stalling is not the source of the real-time deadline miss.
2. Identify all SDMA transfers to/from L2 memory (e.g., EDMA transfer to/from L2 from/to a McBSP or from/to TCP). If there are no SDMA transfers going to L2, then SDMA/IDMA stalling is not the source of the problem.
3. Redirect all SDMA transfers to L2 memory to other memories using one of the following methods:
  - Temporarily transfer all the L2 SDMA transfers to L1D SRAM.
  - If not all L2 SDMA transfers can be moved to L1D memory, temporarily direct some of the transfers to DDR memory and keep the rest in L1D memory. There should be no L2 SDMA transfers.
  - If neither of the above approaches are possible, move the transfer with the real-time deadline to the EMAC CPPI RAM. If the EMAC CPPI RAM is not big enough, a two-step mechanism can be used to page a small working buffer defined in the EMAC CPPI RAM into a bigger buffer in L2 SRAM. The EDMA module can be setup to automate this double buffering scheme without CPU intervention for moving data from the EMAC CPPI RAM. Some throughput degradation is expected when the buffers are moved to the EMAC CPPI RAM.



**Note**—The EMAC CPPI RAM memory is word-addressable only, and, therefore, must be accessed using an EDMA index of 4 bytes.

If real-time deadlines are still missed after implementing any of the options in Step 3, then SDMA/IDMA stalling is likely not the cause of the problem. If real-time deadline misses are solved using any of the options in Step 3, then SDMA/IDMA stalling is likely the source of the problem.

An extreme manifestation of the IDMA/SDMA stall bug is the C64x+ MDMA-SDMA deadlock that requires a device reset or power-on reset in order for the system to recover. The following summarizes the deadlock conditions:

- Master(s) on a single main MSCR port write to the C64x+'s SDMA followed by a write to slaveX.
- The C64x+ issues victim traffic or a non-cacheable write to slaveX.
- Any one of the following:
  - A write data path pipelined in main MSCR between master(s) and a C64x+
  - SDMA
  - A bridge exists between master(s) and the main MSCR
  - Master(s) are able to issue a command to slaveX concurrent with the write to the C64x+'s SDMA.

**Details:** Under certain conditions, L2 victim traffic due to a block writeback can block SDMA/IDMA accesses to UMAP0 during CPU requests. For a definition of UMAP0 for the C6457 device, see “[Appendix C—UMAP0 and UMAP1 Addresses Ranges](#)”.

There are four transactions that must occur to cause an SDMA/IDMA to stall because of this condition:

1. L1D/L1P needs to create an L2\$ hit. This happens as a result of one of the following:
  - An L1D victim (through L1D writeback or writeback-invalidate)
  - An L1D read+victim (through L1D read miss resulting in a writeback)
  - An L1D write miss (write-through to an uncached line)
  - An L1D read miss
  - An L1P fetch miss
2. A user-initiated L2 block writeback must occur involving the same cache set as the previous L2\$ hit.
3. An SDMA access to UMAP0
4. The CPU also accesses the same cache set as the previous 2 bullets. This happens as a result of a CPU LDx/STx instruction that causes one of the following:
  - • An L1D victim (through L1D writeback or writeback-invalidate)
  - • An L1D write miss (write-through to an uncached line)
  - • An L1D read miss
  - • An L1P fetch miss

As a result of the four steps above, any further SDMA to UMAP0 are blocked. SDMA to UMAP1 are unaffected. Again, note that the three of these items **MUST** involve the same L2\$ set in order to see the issue and thus is not as likely as the other conditions listed in the original errata. The stall will persist until the operations above are complete.

**Workaround 1:** As mentioned in the background material above, issues such as dropped McBSP samples can be worked around by moving latency-sensitive buffers outside the C64x+ megamodule. For example, rather than placing buffers for the McBSP into L1/L2, those buffers can instead be placed in other memory, such as the EMAC CPPI RAM.




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**Note**—The EMAC CPPI RAM memory is word-addressable only and, therefore, must be accessed using an EDMA index of 4 bytes.

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- Workaround 2:** To reduce the SDMA/IDMA stalling system impact, perform any of the following:
1. Improve system tolerance on DMA side (SDMA/IDMA/MDMA):
    - Understand and minimize latency-critical SDMA/IDMA accesses to L2 or L1P/D.
    - Directly reduce critical real-time deadlines, if possible, at peripheral/IO level (e.g., increase word size and/or reduce bit rates on serial ports).
    - Reduce DSP MDMA latency:
      - › Increase the priority of the DSP access to DDR2 such that MDMA latency of MDMA accesses causing stalls is minimized.



**Note**—Note: Other masters may have real-time deadlines that dictate higher priority than the DSP.

- › Lower the PRIO\_RAISE field setting in the DDR2 memory controller's burst priority register. Values ranging between 0x10 and 0x20 should give adequate performance and minimize latency; lower values may cause excessive SDRAM row thrashing. Minimize offending scenarios on DSP/caching side:
  - If the DSP performing non-cacheable writes is causing the issue, insert protected non-cacheable reads (as shown in the last list item below) every few writes to allow the write buffer to empty.
  - Use explicit cache commands to trigger cache writebacks during appropriate times (L1D Writeback All, L2 Writeback All). Do not use these commands when real-time deadlines must be met.
  - Restructure program data and data flow to minimize the offending cache activity.
    - › Define the read-only data as const. The const C keyword tells the compiler not to write to the array. By default, such arrays are allocated to the .const section as opposed to BSS. With a suitable linker command file, the developer can link the .const section off chip, while linking .bss on chip. Because programs initialize .bss at run time, this reduces the program's initialization time and total memory image.
    - › Explicitly allocate lookup tables and writeable buffers to their own sections. The #pragma DATA\_SECTION (label, section) directive tells the compiler to place a particular variable in the specified COFF section. The developer can explicitly control the layout of the program with this directive and an appropriate linker command file.
    - › Avoid directly accessing data in slow memories (e.g., flash); copy at initialization time to faster memories.
- Modify troublesome code.
  - › Rewrite using DMAs to minimize data cache writebacks. If the code accesses a large quantity of data externally, consider using DMAs to bring in the data, using double buffering and related techniques. This will minimize cache write-back traffic and the likelihood of SDMA/IDMA stalling.

- › Re-block the loops. In some cases, restructuring loops can increase reuse in the cache and reduce the total traffic to external memory.
- › Throttle the loops. If restructuring the code is impractical, then it is reasonable to slow it down. This reduces the likelihood that consecutive SDMA/IDMA blocks stack up in the cache request pipelines, resulting in a long stall.
- Protect non-cacheable reads from generating an SDMA stall by freezing the L1D cache during the non-cacheable read access(es).
  - › The `long_dist_load_word` function (please see the code listing for `ldld.asm` provided in section of [Appendix A—Code Examples](#)) is suitable for isolated accesses, contains a function that protects non-cacheable reads, avoids blocking during the reads, and, therefore, avoids the deadlock state.

**Workaround 3:** Entirely eliminate the exception by removing all SDMA/IDMA accesses to L2 SRAM.

For example, EMAC descriptors and EMAC payload cannot reside in L2. Master peripherals like the EDMA/QDMA, IDMA, and SRIO cannot access L2. There are no issues with the CPU itself accessing code/data in L2. This issue only pertains to SDMA/IDMA accesses to L2.

### Deadlock Avoidance

To avoid the manifestation of a C64x+ deadlock, several workarounds: are suggested depending on the VBUSM master in question ([Table 8](#)):

**Table 8 VBUSM Masters and Associated Workarounds**

VBUSM Master	Workaround
EDMA3TCx	Inbound and outbound traffic should be programmed on different TC ports (i.e. two different EDMA queues, because a given queue maps to a given TC). Note that in-/out-bound direction is defined as the write direction, meaning that a DDR2-to-DDR2 transfer is outbound and L2-to-L2 is inbound. Any TC used to write to DDR should not be used to write to a megamodule even when the TC writing to the DDR is also reading from DDR.
EMAC	EMAC should write to the megamodule's memory or the DDR, but not both. This includes buffers and buffer descriptors. EMAC CPPI descriptors should be placed entirely in the local wrapper memory, any combination of wrapper and L2 memory (must match other master transactions), or any combination of wrapper and DDR2 SDRAM (must match other master transactions). Buffer descriptors should not be placed in any combination of L2 and DDR2 SDRAM.
SRIO	SRIO should transfer payload data only to megamodule memories or to DDR2 SDRAM, but not both. This includes any direct I/O writes as well as any inbound RX messaging transfer.
SRIO CPPI	SRIO CPPI descriptors should be placed entirely in the local wrapper memory, any combination of wrapper and L2 memory, or any combination of wrapper and DDR2 SDRAM. Buffer descriptors should not be placed in any combination of L2 and DDR2 SDRAM.
<b>End of Table 8</b>	

## Advisory 10 **L1P\$ Miss May Block SDMA Accesses (Asymmetric Mode Only)**

**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** This advisory is an update to [Advisory 9](#) in this document. [Advisory 9](#) lists the following blocking condition:

- Stall Condition 1 - L2 victim traffic due to L2 block writeback during any pending CPU request

This advisory covers one more blocking condition:

- Stall Condition 2 - L1P\$ miss may stall SDMA accesses

For silicon versions 1.0, 1.1, and 1.2 that contain the original SDMA/IDMA blocking advisory, this is a second way to hit the SDMA/IDMA stall in addition to the previously communicated errata conditions in [Advisory 9](#).

No additional deadlock risk potential is created by the addition of the new bug to silicon 1.0, 1.1, and 1.2 that currently contain the first SDMA/IDMA blocking condition (described in [Advisory 9](#)). That means that this new issue can lead to a deadlock in the same manner that the other condition can. On silicon revision 1.3 without the original stall condition, this creates a deadlock condition that is identical to the previous revisions.

**Table 9 C6457 Silicon Revisions and SDMA/IDMA Stall Conditions**

Silicon Revision	Stall Condition 1	Stall Condition 2
Rev 1.2 and earlier	YES	YES
Rev 1.3	NO	YES
Rev 1.4	NO	NO
<b>End of Table 9</b>		

Under certain conditions, L2 accesses to external memory resulting from an L1P\$ miss can block SDMA/IDMA accesses during CPU/DMA requests. There are several transactions that must happen to cause an SDMA/IDMA to stall because of this condition:

- A DMA access to UMAP0
- An L1D\$ read miss from UMAP0<sup>1</sup>
- An L1D\$ write or victim to UMAP1. This happens as a result of one of the following:
  - An L1D victim (through L1D writeback or writeback-invalidate) to UMAP1
  - An L1D read+victim (through L1D read miss resulting in a writeback) to any L2<sup>2</sup>
  - An L1D write miss (write-through to an uncached line)
- An L1P\$ miss that results in an L2 access to external memory. L2 victim can create deadlock or preceding long distance write.<sup>3</sup>
- An SDMA access to UMAP<sup>4, 5</sup>

1.Note that if SW is currently running in L1D\$ Freeze Mode during this transaction, transaction 1 is not needed to reproduce this issue.

2.The victim generated still needs to go to UMAP1. The reason that the L1D\$ read can be to any L2 address (UMAP0 or UMAP1) is that there is no way of knowing if the least recently used cache line that will be evicted is in UMAP0 or UMAP1.

3.This step may not be necessary if a long distance write to external memory is currently pending.

4.It is also important to note that without step 5, this issue does not exist. That means that if the resolution of the pipeline is completed before (5), then the issue is not seen.

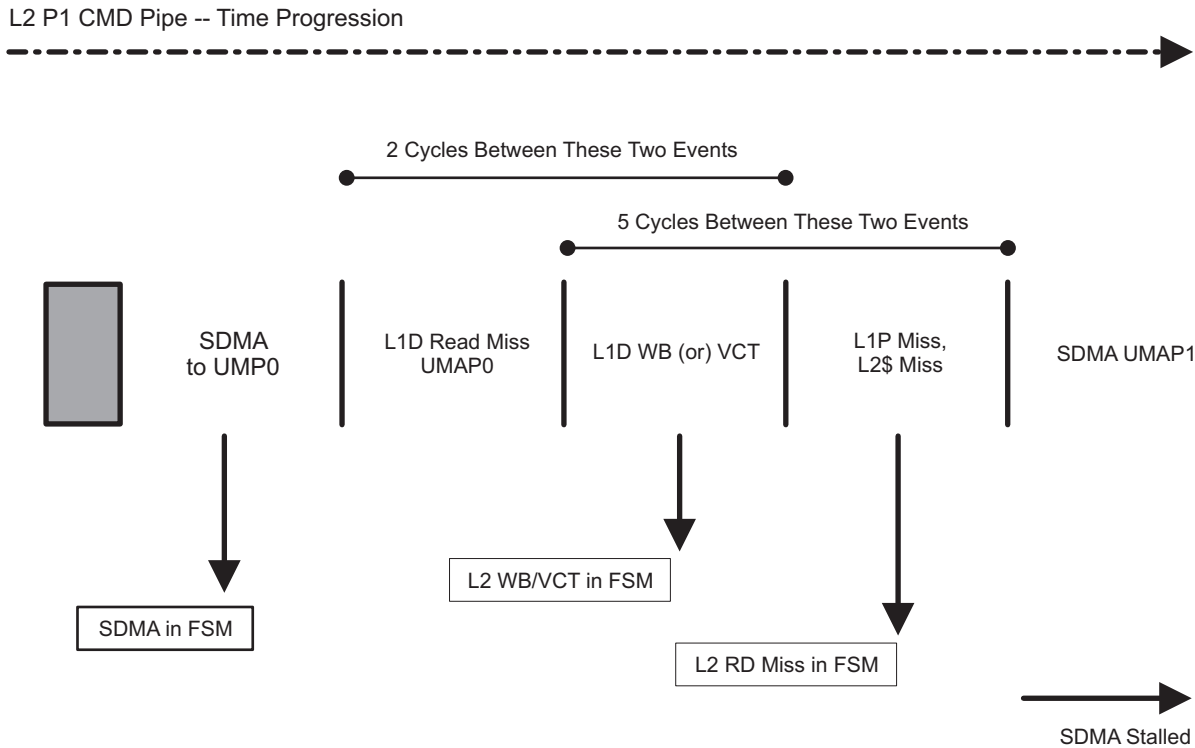
5.If an SDMA access to UMAP0 occurs before transaction (5), the pipeline is flushed and this issue is not seen.

The SDMA in item 1 sets up a bank conflict for the L1D\$ read in item 2. The L1D\$ allocate in item 2 prevents the L1D\$ write/victim (3) from advancing, so it is stuck in the pipeline. This occurs at the same time as an L1P\$ allocate that also results in an L2 access to external memory (4), which is also in the same pipeline stage as the L1D\$ write/victim (3). At this point, the L1P\$ allocate (4) advances to the next pipeline stage but the L1D\$ write/victim (3) is still stuck waiting on the L1D\$ allocate (2). This now sets up the pipeline for the stall condition, which is actually triggered by an SDMA to UMAP1 (5). This is what causes further SDMAs to stall. After the L1P\$ allocate (4) is complete, (2) resolves, allowing (3) to resolve thus freeing the SDMA pipeline again. Therefore, the stall is effectively for the length of the L1P\$ allocate in item (4).

Please note that the above four conditions do not guarantee that a stall will occur, it may stall depending on the timing between the transactions. Steps 2 and 3 must occur within two CPU cycles of each other and steps 3 and 4 must occur within five CPU cycles of each other.

Figure 6 shows this timing relationship.

**Figure 6 L2 P1 CMD Pipe – Time Progression**



**Workaround 1:** Leave in previous SDMA/IDMA stall workarounds (for devices with the original SDMA/IDMA stall).

For silicon versions 1.0, 1.1, and 1.2 that were already affected with the first SDMA/IDMA stall issue from [Advisory 9](#), there is no additional workaround needed.

If all of the deadlock avoidance steps listed in [Advisory 9](#) have been followed, there is no risk for a deadlock because of this issue. Methods to reduce stalling due to this issue are also already covered in advisory [Advisory 9](#).

For silicon version 1.3 that fixed the initial condition of SDMA/IDMA stall issue, the deadlock avoidance steps that are already listed in [Advisory 9](#) for previous revisions of silicon should be followed to ensure there is no chance of a deadlock. The workarounds to avoid stalls are also the same as communicated in previous revisions of the device with the issue.

**Workaround 2:** Do not place program code in external memory.

This issue can be avoided by either ensuring that all program code is in L1P or L2 SRAM or SL2 SRAM. This eliminates the possibility of creating an L1P\$ miss that generates an L2 read from external memory.

**Workaround 3:** Allocate all CPU writeable DMA buffers/variables in UMAP0 or L1D RAM.



**Note**—DMA in this case refers to EDMA and other masters external to the C64x+ megamodule.

If possible, move DMA buffers that are also writeable by the CPU to completely reside in UMAP0 or L1D RAM. This prevents SDMA traffic to multiple UMAP ports.

**Workaround 4:** Allocate CPU Data Buffers/Variables in UMAP0.

If possible, move CPU data buffers/variables out of UMAP1 to UMAP0. This eliminates the CPU data accesses to/from UMAP1. Please see [“Appendix C—UMAP0 and UMAP1 Addresses Ranges”](#).

**Workaround 5:** Allocate CPU-readable Data Buffers/Variables in UMAP1.



**Note**—Because the L2\$ is located in UMAP0, this workaround assumes that L2\$ is disabled.

If possible, move CPU-readable data buffers/variables out of UMAP0 to UMAP1. This eliminates the CPU data reads from UMAP0. CPU writes to UMAP1 are OK. Again, please see [“Appendix C—UMAP0 and UMAP1 Addresses Ranges”](#).

**Usage Note 1****Manual Cache Coherence Operation Usage Note**

---

**Revision(s) Affected:** 1.3, 1.2, 1.1, 1.0

**Details:** When an L1DWB, L1DWBINV, L2DWB, or L2DWBINV command is executed, and the writeback is complete, the C64x+ Megamodule will send a single 128-bit message with the address of the last word that the block operation was for. On OMAP devices, the extra sideband signal mentioned above is used to route that to a special endpoint. On the HPMP devices, TI did not hook up this signal and therefore this looks like any other write command.

Because CPU to CPU transfers are not allowed in the connectivity of the SCR, the address is treated as an invalid address and the command is immediately terminated at the null-endpoint within the SCR and goes nowhere. There should be no effect at all to the system by this behavior.

**Workaround 1:** No workaround is available as there is no effect on the system by this behavior.

## Appendix A—Code Examples

### L1D Block Writeback Routine `l1d_block_wb.asm`

```

;; ===== ;
;; L1D Block Writeback ;
;; ;
;; l1d_block_wb(void *base, size_t byte_count); ;
;; ;
;; Performs a block writeback from L1D to L2. It can be used ;
;; on any address range (L2 or external), but it only operates on L1D ;
;; cache. ;
;; ;
;; Maximum block size is 256K. Exact maximum byte count depends on the ;
;; alignment of the block. ;
;; ;
;; Interrupts are disabled during the block writeback operation. ;
;; ===== ;

    .asg 0x01844040, L1DW ; L1D Block Wb; BAR at 0, WC at 1
    .global _l1d_block_wb
    .text
    .asmfunc
_l1d_block_wb:

    MVC DNUM, B0 ; \_ Get global alias prefix
    ADDK 0x10, B0 ; /
    SHRU A4, 24, B2 ; Get prefix from address
    CMPEQ B0, B2, B0 ; Check if address prefix is global
[B0] EXTU A4, 8, 8, A4 ; Remove global prefix from address
    MVKL L1DW, B6 ;

    CLR A4, 0, 5, A1 ; Align to L1D cache line boundary
|| ADD A4, B4, B1 ; Compute end of buffer

    ADDK 63, B1 ; \_ Round to next L1D cache line
    CLR B1, 0, 5, B1 ; /

    SUB B1, A1, B1 ; Count cache-line span in bytes
|| MVKH L1DW, B6 ;

    SHR B1, 2, B1 ; Convert to "word count"
|| DINT ; Disable interrupts

    STW A1, *B6[0] ; Store base address
    STW B1, *B6[1] ; Store word count
    ; Note: The following loop is intentionally low-rate to avoid
    ; interfering with the block writeback operation.
loop: LDW *B6[1], B1 ; Read remaining word-count
    NOP 4
    [ B1] BNOP loop, 5 ; Loop until done

    RINT ; Reenable interrupts
    RETNOP B3, 5 ; Return to caller
    .endasmfunc

;; ===== ;
;; End of file: l1d_block_wb.asm ;
;; ===== ;

```

## L1D Block Writeback-Invalidate Routine `l1d_block_wbinv.asm`

```

;; ===== ;;
;; L1D Block Writeback-Invalidate ;;
;; ;;
;; l1d_block_wbinv(void *base, size_t byte_count); ;;
;; ;;
;; Performs a block writeback-invalidate from L1D to L2. It can be used ;;
;; on any address range (L2 or external), but it only operates on L1D ;;
;; cache. ;;
;; ;;
;; Maximum block size is 256K. Exact maximum byte count depends on the ;;
;; alignment of the block. ;;
;; ;;
;; Interrupts are disabled during the block writeback operation. ;;
;; ===== ;;

    .asg 0x01844030, L1DWI      ; L1D Block Wb-Inv; BAR at 0, WC at 1
    .global _l1d_block_wbinv
    .text
    .asmfunc
_l1d_block_wbinv:
    MVC DNUM, B0              ; \_ Get global alias prefix
    ADDK 0x10, B0             ; /
    SHRU A4, 24, B2           ; Get prefix from address
    CMPEQ B0, B2, B0          ; Check if address prefix is global
[B0] EXTU A4, 8, 8, A4        ; Remove global prefix from address
    MVKL L1DWI, B6 ;

    CLR A4, 0, 5, A1          ; Align to L1D cache line boundary
|| ADD A4, B4, B1             ; Compute end of buffer

    ADDK 63, B1               ; \_ Round to next L1D cache line
    CLR B1, 0, 5, B1          ; /

    SUB B1, A1, B1 ; Count cache-line span in bytes
|| MVKH L1DWI, B6 ;

    SHR B1, 2, B1             ; Convert to "word count"
|| DINT                       ; Disable interrupts

    STW A1, *B6[0] ; Store base address
    STW B1, *B6[1] ; Store word count
    ; Note: The following loop is intentionally low-rate to avoid
    ; interfering with the block writeback operation.
loop: LDW *B6[1], B1          ; Read remaining word-count
    NOP 4
[B1] BNOP loop, 5 ; Loop until done

RINT                          ; Reenable interrupts
RETNOP B3, 5 ; Return to caller
    .endasmfunc

;; ===== ;;
;; End of file: l1d_block_wbinv.asm ;;
;; ===== ;;

```

## Make Buffer Dirty Routine `make_dirty`

```

;; ===== ;;
;; Make a block of data "dirty" in L1D ;;
;; ;;
;; make_dirty(void *base, size_t byte_count); ;;
;; ;;
;; ===== ;;

        .global _make_dirty
        .text
        .asmfunc
_make_dirty:
        ADDK 63, B4
        SHR B4, 6, B4
        MVC B4, ILC
        MVK 64, A5
        MVK 64, B5
        MV A4, B4
        NOP
        SPLLOOP 1
        LDBU *A4++[A5], A1
        NOP 4
        MV.L A1, B1
        STB B1, *B4++[B5]
        SPKERNEL

        RETNOP B3, 5

        .endasmfunc
;; ===== ;;
;; End of file: make_dirty.asm ;;
;; ===== ;;

```

## Long Distance Load Word Routine ldlld.asm

```

;; ===== ;;
;; Long Distance Load Word ;;
;; ;;
;; int long_dist_load_word(volatile int *addr) ;;
;; ;;
;; This function reads a single word from a remote location with the L1D ;;
;; cache frozen. This prevents L1D from sending victims in response to ;;
;; these reads, thus preventing the L1D victim lock from engaging for the ;;
;; corresponding L1D set. ;;
;; ;;
;; The code below does the following: ;;
;; ;;
;; 1. Disable interrupts ;;
;; 2. Freeze L1D ;;
;; 3. Load the requested word ;;
;; 4. Unfreeze L1D ;;
;; 5. Restore interrupts ;;
;; ;;
;; Interrupts are disabled while the cache is frozen to prevent affecting ;;
;; the performance of interrupt handlers. Disabling interrupts during ;;
;; the long distance load does not greatly impact interrupt latency, ;;
;; because the CPU already cannot service interrupts when it's stalled by ;;
;; the cache. This function adds a small amount of overhead (~20 cycles) ;;
;; to that operation. ;;
;; ;;
;; ===== ;;

    .asg 0x01840044, L1DCC ; L1D Cache Control
    .global _long_dist_load_word
    .text
    .asmfunc
; int long_dist_load_word(volatile int *addr)
_long_dist_load_word:
    MVKL L1DCC, B4
    MVKH L1DCC, B4
    | DINT ; Disable interrupts
    | MVK 1, B5
    STW B5, *B4 ; \_ Freeze cache
    LDW *B4, B5 ; /
    NOP 4
    SHR B5, 16, B5 ; POPER -> OPER
    | LDW *A4, A4 ; read value remotely
    NOP 4
    STW B5, *B4 ; \_ Restore cache
    RET B3
    | LDW *B4, B5 ; /
    NOP 4
    RINT ; Restore interrupts
    .endasmfunc

;; ===== ;;
;; End of file: ldlld.asm ;;
;; ===== ;;

```

**IDMA Channel 1 Block Copy Routine idma1\_util.asm**

```

;; ===== ;
;; TEXAS INSTRUMENTS INC. ;
;; ;
;; Block Copy with IDMA Channel 1 ;
;; ;
;; REVISION HISTORY ;
;; 13-Feb-2009 Initial version . . . . . J. Zbiciak ;
;; ;
;; DESCRIPTION ;
;; The following macro functions are defined in this file: ;
;; ;
;; idma1_copy(void *dst, void *src, int word_count) ;
;; idma1_wait(IDMA_PEND or IDMA_ACTV) ;
;; ;
;; NOTE: The last arg is WORD count, not byte count. 1 word = 4 bytes. ;
;; ;
;; ----- ;
;; Copyright (c) 2009 Texas Instruments, Incorporated. ;
;; All Rights Reserved. ;
;; ===== ;

    .asg 0x01820100, IDMA1_STATUS
    .asg 0x01820108, IDMA1_SOURCE
    .asg 0x0182010C, IDMA1_DEST
    .asg 0x01820110, IDMA1_COUNT
    .asg 0x01820100, IDMA1_BASE
    .asg (IDMA1_STATUS - IDMA1_BASE), OFS_IDMA1_STATUS
    .asg (IDMA1_SOURCE - IDMA1_BASE), OFS_IDMA1_SOURCE
    .asg (IDMA1_DEST - IDMA1_BASE), OFS_IDMA1_DEST
    .asg (IDMA1_COUNT - IDMA1_BASE), OFS_IDMA1_COUNT

;; ----- ;
;; IDMA1_COPY: Copy a block of words to dst from src with IDMA channel 1 ;
;; ;
;; USAGE ;
;; idma1_copy( <dest address>, <source address>, <word count>) ;
;; ;
;; Both source and destination addresses must be word aligned. ;
;; ;
;; The IDMA gets issued at top priority. Only bits 13:0 of the word ;
;; count are significant. ;
;; ----- ;

    .global _idma1_copy
    .asmfunc
_idma1_copy:
; Point to IDMA channel 1's base
RET B3 ; return; also protect from interrupts
|| MVKL IDMA1_SOURCE, A7
MVKH IDMA1_SOURCE, A7
; Write second argument to "source" register
STW B4, *A7++(IDMA1_DEST - IDMA1_SOURCE)
; Write first argument to "destination" register
STW A4, *A7++(IDMA1_COUNT - IDMA1_DEST)
; Write last argument to "count" register.
EXTU A6, 18, 16, A6 ; truncate word count to 14 bits
STW A6, *A7
    .endasmfunc

;; ----- ;
;; IDMA1_WAIT: Wait for IDMA "pend" or "actv" slot to free up. ;
;; ;
;; USAGE ;
;; idma1_wait(IDMA_PEND) Waits for just PEND to be 0 ;
;; idma1_wait(IDMA_ACTV) Waits for ACTV (and PEND) to be 0 ;
;; ;
;; NOTE ;
;; IDMA_PEND = 2 ;
;; IDMA_ACTV = 3 ;
;; ----- ;

    .global _idma1_wait
    .asmfunc
_idma1_wait:
    MVKL IDMA1_STATUS, A6
    MVKH IDMA1_STATUS, A6
    || MVK 1, A0
loop?:

```

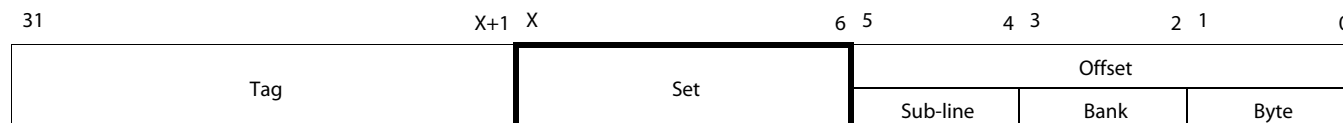
```
[ A0] LDW *A6, A0
|| [ A0] BNOP.1 loop?, 4
; The 'AND' below is safe because IDMA never returns 10b in 2 LSBs
AND.L A4, A0, A0
RETNOP B3, 5
.endasmfunc

;; ===== ;;
;; End of file: idma1_util.asm ;;
;; ===== ;;
```

## Appendix B—Determining If Two Addresses are a Set Match

Determining if two addresses are a set match can be done by comparing certain bits of two addresses. The mapping of an address to a location in L1D cache is shown in Figure 7.

**Figure 7** L1D Cache Address Mapping



The value X in Figure 7 is determined by how large the L1D cache is in the particular application (see Table 10).

**Table 10** Value of X for L1D Cache

Amount of L1D Cache	X Bit Position
0 KB	N/A
4 KB	10
8 KB	11
16 KB	12
32 KB	13
<b>End of Table 10</b>	

If the user uses the default configuration, 32 KB, as an example, bits [13:6] are a set match if they are identical in two different addresses. Some examples of set matches are shown below:

- 0x0080 2A80 - 0b000000001000000000**10101010**0000000
- 0x8000 2A80 - 0b100000001000000000**10101010**0000000
- 0x0080 2A8A - 0b000000001000000000**10101010**0001010

## Appendix C—UMAP0 and UMAP1 Addresses Ranges

The below tables detail the address ranges of UMAP0 and UMAP1 for the C6457 device.

**Table 11 UMAP0 Address Range for C6457**

UMAP0	Address Range <sup>1</sup>
RAM	0x00900000 - 0x009FFFFFF
<b>End of Table 11</b>	

1. Please note that L2 cache, if used, is a portion of the address range.

**Table 12 UMAP1 Address Range for C6457**

UMAP1	Address Range
RAM	0x00800000 - 0x008FFFFFF
<b>End of Table 12</b>	

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DLP® Products	<a href="http://www.dlp.com">www.dlp.com</a>	Communications and Telecom	<a href="http://www.ti.com/communications">www.ti.com/communications</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Computers and Peripherals	<a href="http://www.ti.com/computers">www.ti.com/computers</a>
Clocks and Timers	<a href="http://www.ti.com/clocks">www.ti.com/clocks</a>	Consumer Electronics	<a href="http://www.ti.com/consumer-apps">www.ti.com/consumer-apps</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Energy	<a href="http://www.ti.com/energy">www.ti.com/energy</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Industrial	<a href="http://www.ti.com/industrial">www.ti.com/industrial</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Medical	<a href="http://www.ti.com/medical">www.ti.com/medical</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
RFID	<a href="http://www.ti-rfid.com">www.ti-rfid.com</a>	Space, Avionics & Defense	<a href="http://www.ti.com/space-avionics-defense">www.ti.com/space-avionics-defense</a>
RF/IF and ZigBee® Solutions	<a href="http://www.ti.com/lprf">www.ti.com/lprf</a>	Video and Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>
		Wireless	<a href="http://www.ti.com/wireless-apps">www.ti.com/wireless-apps</a>

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